

Numerical analysis for the BCF method in complex fluids simulations

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Joint work with Weinan E and Pingwen Zhang

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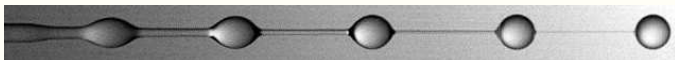
Outline

Introduction

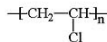
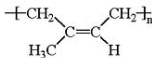
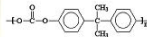
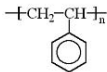
Numerical analysis

Polymeric fluids

- ▶ Complex fluids: **viscoelastic** fluids containing many macromolecules.



- ▶ Anomalous viscoelastic properties: shear thinning, shear thickening, tubeless siphon, Rod climbing, etc.
- ▶ Many industrial usage: liquid crystal display, synthesized products (CD, ...), plastics, ...



Mathematical models (solution case)

- ▶ Newtonian fluid (Linear constitutive relation)

$$\begin{cases} \mathbf{u}_t + (\mathbf{u} \cdot \nabla)\mathbf{u} + \nabla p &= \nabla \cdot \boldsymbol{\tau}, \\ \nabla \cdot \mathbf{u} &= 0, \end{cases}$$

where $\boldsymbol{\tau} = \boldsymbol{\tau}_s = \eta_s(\nabla\mathbf{u} + \nabla\mathbf{u}^T)$.

- ▶ Non-Newtonian fluid (Nonlinear constitutive relation)

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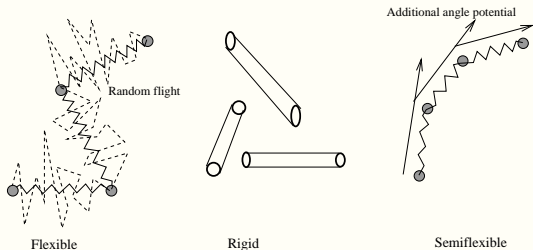
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Coarse graining of polymers

- ▶ Molecular dynamics: limited space and time scales
- ▶ Macroscopic modelling: neglecting all of the molecular details
- ▶ **Compromise: kinetic theory**
Bending persistence length: l_p
Length of one single polymer: l



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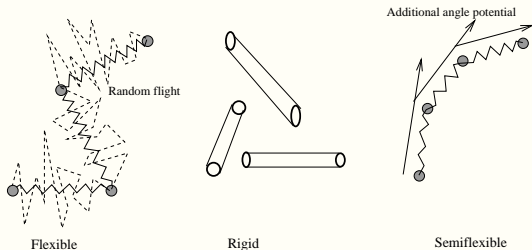
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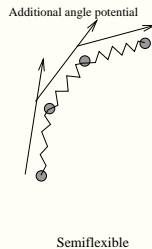
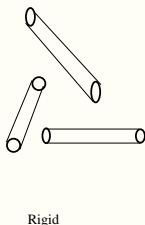
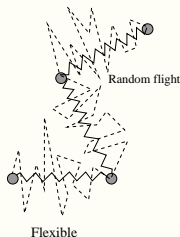
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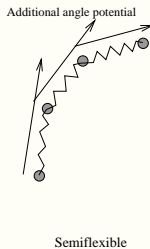
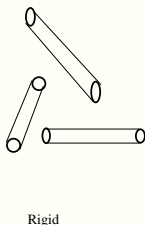
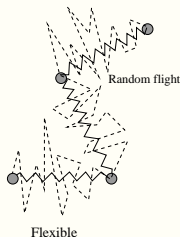
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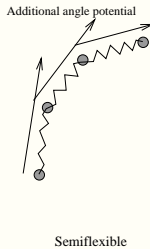
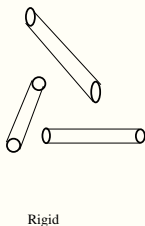
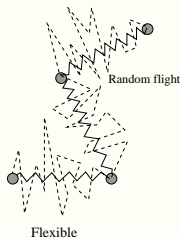
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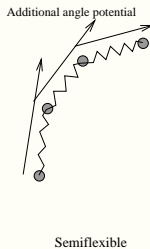
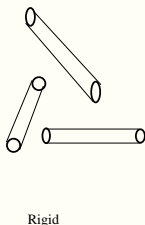
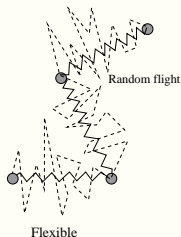
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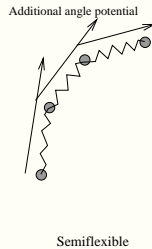
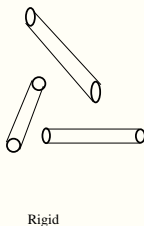
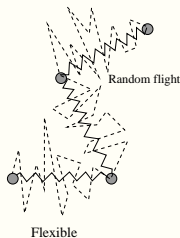
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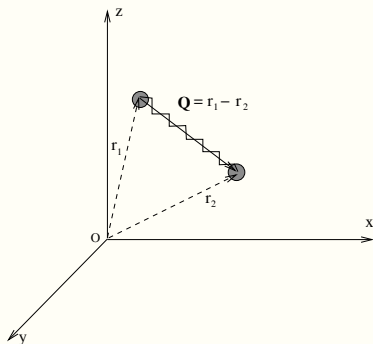
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Simplest flexible polymers

- Dumbbell model



Dumbbell model (dilute limit)

- ▶ Stochastic differential equations (homogeneous approximation, mean position)

$$\begin{cases} dx &= u dt \\ dQ &= (\kappa Q - \frac{2}{\zeta} F(Q)) dt + \sqrt{\frac{4k_B T}{\zeta}} dW \end{cases}$$

- ▶ Kramers Expression: $\tau_p = -nk_B T I + n \langle F(Q) \otimes Q \rangle$
- ▶ Spring force

- ▶ A coupled deterministic-stochastic system (u and Q).

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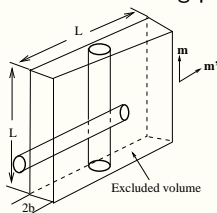
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SDE for liquid crystal (high concentration case)

- ▶ Rod model for liquid crystals: an interacting particle system.



- ▶ The non-dimensionalized form for pdf ψ : (U is usually taken as mean field potential, $\mathcal{R} = m \times \nabla_m$.)

$$\partial_t \psi = \frac{1}{De} \mathcal{R} \cdot (\mathcal{R} \psi + \psi \mathcal{R} U) - \mathcal{R} \cdot (m \times \kappa \cdot m \psi).$$

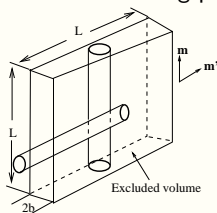
- ▶ The corresponding stochastic version: nonlinear SDEs in the sense of McKean.

$$\frac{\partial m}{\partial t} + (u \cdot \nabla_x) m = (I - m \otimes m) \circ \left(-\frac{1}{De} \mathcal{R} U + m \times \kappa \cdot m + \sqrt{\frac{2}{De}} \dot{W}(t) \right),$$

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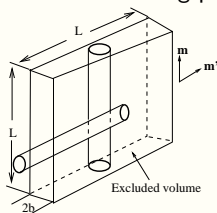
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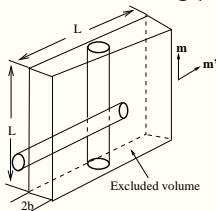
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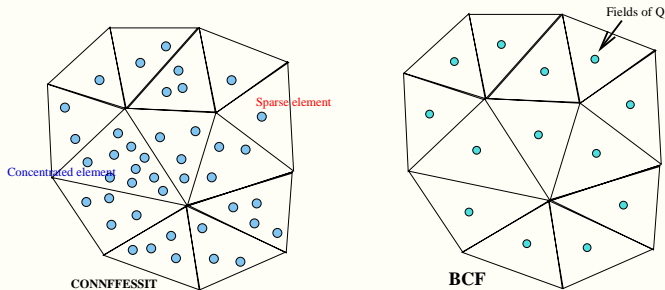
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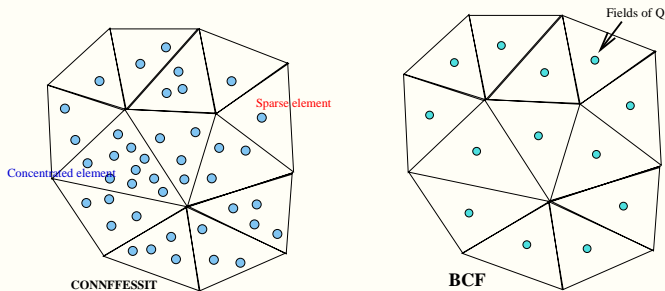


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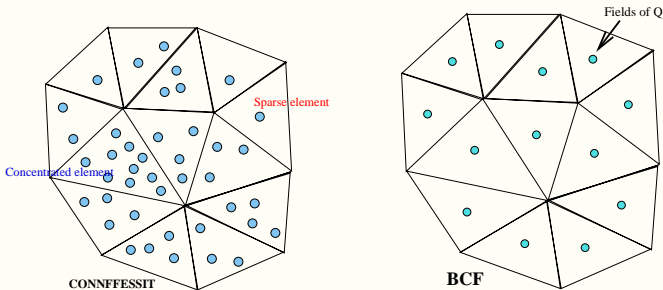
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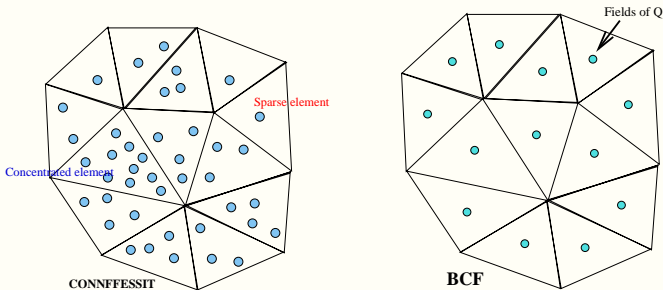
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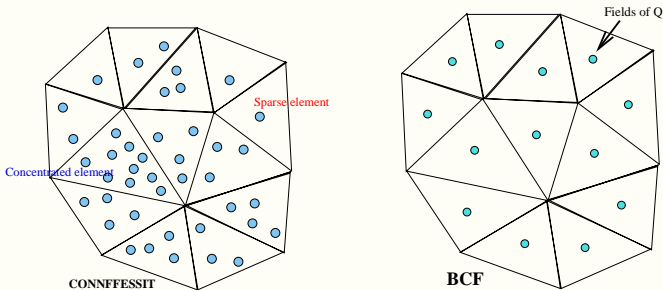
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An overview of the results for the BCF methods

- ▶ Well-posedness analysis
 - ▶ Hookean dumbbell under shear flow: [Jourdain-Lelievre-Le Bris \(2002\)](#)
 - ▶ FENE dumbbell under shear flow: [Jourdain-Lelievre-Le Bris \(2004\)](#)
 - ▶ General dumbbell model, high dim with polynomial growth: [E-Li-Zhang \(2004\)](#)
- ▶ Convergence analysis
 - ▶ Hookean dumbbell under shear flow: [Jourdain-Lelievre-Le Bris, E-Li-Zhang \(2002\)](#)
 - ▶ Rod-like model under shear flow: [Li-Zhang-Zhou \(2004\)](#)
 - ▶ High dimensional Hookean dumbbell model: [Li-Zhang \(2005\)](#)
 - ▶ Nonlinear dumbbell: Only partial results.

Simple SDE and discretization

- ▶ Simple SDE

$$dX_t = b(X_t)dt + dW_t$$

- ▶ Euler-Maruyama scheme

$$X_{n+1} = X_n + \Delta t b(X_n) + \Delta W_n$$

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BCF scheme for Hookean dumbbell under shear flow

- ▶ Discretized equations (temporal and stochastic)

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A new type of convergence

► Coupling issue

The errors e^n are random variables!

$$\mathbb{E}\|e_y^{n+1}\|_{L_y^2}^2 \langle (\hat{Q}^n)^2 \rangle_N \neq \mathbb{E}\|e_y^{n+1}\|_{L_y^2}^2 \mathbb{E}\langle (\hat{Q}^n)^2 \rangle_N$$

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$$\Delta t \langle (\hat{Q}^n)^2 \rangle_N \leq \frac{1}{2}$$

after excluding a set \mathcal{A} of exponentially small probability.

► Mean square convergence after excluding a set of exponentially small probability

$$\mathbb{E}\left(\|e^n\|_{L_y^2}^2 \cdot \mathbf{1}_{\mathcal{A}^c}\right) \leq \Delta t^2 + \frac{1}{N}.$$

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BCF for Liquid Crystal Polymers

- ▶ SDE form for Doi-Edwards model (shear flow, 1D)

$$d\Theta_t = -\left(a(\Theta_t, \mathcal{L}(\Theta_t)) + \partial_y u \sin^2 \Theta_t\right) dt + dW_t,$$

$$\tau(y, t) = \mathbb{E} \left[\sin 2\Theta_t + a(\Theta_t, \mathcal{L}(\Theta_t)) \cos^2 \Theta_t + \partial_y u \sin^2 2\Theta_t \right],$$

where $a(\Theta_t, \mathcal{L}(\Theta_t)) = \int_{-\infty}^{+\infty} \sin 2(\Theta_t - \theta') \mathcal{L}(\Theta_t)(d\theta')$.

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becomes

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Convergence analysis for Liquid Crystal Polymers

- ▶ Convergence result (**without excluding the small set**)

$$\mathbb{E} \left| \mathbb{E} f(\Theta_t) - \frac{1}{N} \sum_{j=1}^N f(\Theta_t^j) \right|^2 \leq \frac{C}{N}$$

This mean square convergence is due to the **boundedness of sin function**, which is quite special for this problem.

- ▶ Techniques (A.-S. Sznitman, LNM 1464 (1991))
 - Wasserstein metric for iterative convergence.
 - Centering for mean square convergence.

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High-D convergence analysis for dumbbell model

Define the error

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$$\int_D \mathbf{u}^n \cdot \nabla \mathbf{E}^{n+1} \cdot \mathbf{E}^{n+1} dx = 0$$

► In order to estimate $\int_D \mathbf{e}^n \cdot \nabla \hat{\mathbf{Q}}^{n+1} \cdot \mathbf{E}^{n+1} dx$, one needs

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Difficult! L^2 -type estimate $\| \langle |\nabla \hat{\mathbf{Q}}^{n+1}|^2 \rangle_N \|_{L^2} \leq \text{Const.}$ is easy.

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Essential ingredient 1: Explicit solution for Q

- ▶ SPDE for Q

$$dQ + \mathbf{u} \cdot \nabla Q = (\kappa Q - Q)dt + dW$$

- ▶ Introduce flow map

$$\frac{d\mathbf{x}(\alpha, t)}{dt} = \mathbf{u}(\mathbf{x}(\alpha, t), t), \quad \mathbf{x}(\alpha, 0) = \alpha.$$

and deformation tensor

$$F(\alpha, t) = \frac{\partial \mathbf{x}}{\partial \alpha}, \quad \text{i.e. } F_{ij} = \frac{\partial x_i}{\partial \alpha_j}$$

- ▶ Explicit solution in Lagrangian coordinates

$$Q(\alpha, t) = e^{-t} F(\alpha, t) Q_0(\alpha) + F(\alpha, t) \cdot \int_0^t e^{s-t} F^{-1}(\alpha, s) \cdot dW_s.$$

- ▶ Q is a Gaussian process with S.P.D. covariance matrix. This allows large deviation estimates.

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Essential ingredient 2: Strang's trick for estimating L_h^∞ norm

- ▶ Inverse inequality **under spatial discretization**

$$\|\mathbf{u}^n\|_{L_h^\infty} \leq h^{-\frac{d}{2}} \|\mathbf{u}^n\|_{L_h^2}, \quad \|\tilde{\mathbf{Q}}^n\|_{L_h^\infty} \leq h^{-\frac{d}{2}} \|\tilde{\mathbf{Q}}^n\|_{L_h^2}$$

- ▶ Continuation technique

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If $p > \frac{d}{2}$, $\|\mathbf{u}_h^n\|_{L_h^\infty}$ is bounded.

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A stronger convergence result for high dimensional Hookean dumbbell model

- ▶ Final convergence result

$$\|e^{\cdot, n+1}\|_{L_h^2}^2 + \left\langle \|E^{\cdot, n+1}\|_{L_h^2}^2 \right\rangle_N \preceq C(\delta t^2 + h^4 + \frac{1}{N^{1-\epsilon}})$$

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Nonlinear dumbbells: shear flow (decoupled case)

- ▶ Difficulties: non-Lipschitz property of the force \mathbf{F}

$$d\mathbf{Q}_t = (\kappa \cdot \mathbf{Q}_t - \mathbf{F}(\mathbf{Q}))dt + d\mathbf{W}_t$$

- ▶ One sided Lipschitz condition!

$$(\mathbf{F}(a) - \mathbf{F}(b), a - b) \geq 0 \quad \forall a, b \in \mathbb{R}^m.$$

- ▶ For FENE dumbbell model (implicit method)

$$P^{n+1} = P^n + \left(u_y(t_{n+1})Q^n - \frac{1}{2} \frac{P^{n+1}}{1 - (Q^{n+1})^2/b} \right) \Delta t + dV^n,$$

$$Q^{n+1} = Q^n - \frac{1}{2} \frac{Q^{n+1}}{1 - (Q^{n+1})^2/b} \Delta t + dW^n,$$

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How to construct explicit schemes?

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Nonlinear dumbbells: shear flow (coupled case)

Not available now!

Reference: review paper by Li-Zhang, Comm. Math. Sci. 5 (2007), 1-51.

Thank you!