

# On the Global Regularity of the 3D Navier-Stokes Equations and Relevant Geophysical Models

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# Rayleigh Be'nard Convection / Boussinesq Approximation

- Conservation of Momentum

$$\frac{\partial}{\partial t} \vec{u} - \nu \Delta \vec{u} + (\vec{u} \cdot \nabla) \vec{u} + \frac{1}{\rho_0} \nabla p + f \vec{k} \times \vec{u} = g T \vec{k}$$

- Incompressibility

$$\nabla \cdot \vec{u} = 0$$

- Heat Transport and Diffusion

$$\frac{\partial}{\partial t} T - \kappa \Delta T + (\vec{u} \cdot \nabla) T = 0$$

# Temperature Estimates

- Maximum Principle

$$\|T\|_{L^\infty} \leq C_0 + C_1 \|T_0\|_{L^\infty}$$

- Gradient Estimates

$$\frac{1}{2} \frac{d}{dt} \|\nabla T\|_{L^2}^2 + \kappa \|\Delta T\|_{L^2}^2 = \int (\vec{u} \cdot \nabla) T \cdot \Delta T dx$$

- Estimate of the Nonlinear Term

$$\left| \int (\vec{u} \cdot \nabla) T \cdot \Delta T dx \right| \leq c \|\vec{u}\|_{L^6} \|\nabla T\|_{L^3} \|\Delta T\|_{L^2}$$

- Interpolation/Calculus Inequality

$$\|\varphi\|_{L^3} \leq c \|\varphi\|_{L^2}^{1/2} \|\nabla \varphi\|_{L^2}^{1/2} \quad \forall \varphi \in \dot{H}^1$$

⇒

$$\left| \int (\vec{u} \cdot \nabla) T \cdot \Delta T dx \right| \leq c \|\vec{u}\|_{L^6} \|\nabla T\|_{L^2}^{1/2} \|\Delta T\|_{L^2}^{3/2}$$

- Young's Inequality

$$|a \cdot b| \leq \frac{1}{p} |a|^p + \frac{1}{q} |b|^q, \quad \frac{1}{p} + \frac{1}{q} = 1$$

$$\left| \int (\vec{u} \cdot \nabla) T \cdot \Delta T dx \right| \leq \frac{c}{\kappa^3} \|\vec{u}\|_{L^6}^4 \|\nabla T\|_{L^2}^2 + \frac{\kappa}{2} \|\Delta T\|_{L^2}^2$$

$\Rightarrow$

$$\frac{1}{2} \frac{d}{dt} \|\nabla T\|_{L^2}^2 + \frac{\kappa}{2} \|\Delta T\|_{L^2}^2 \leq \frac{c}{\kappa^3} \|u\|_{L^6}^4 \|\nabla T\|_{L^2}^2$$

By Gronwall's inequality

$$\|\nabla T(t)\|_{L^2}^2 \leq \|\nabla T(0)\|_{L^2}^2 e^{\frac{c}{\kappa^3} \int_0^t \|u(\tau)\|_{L^6}^4 d\tau}$$

## Question:

Is

$$\int_0^t \|u(\tau)\|_{L^6}^4 d\tau \leq K?$$

To answer this question we have to deal with the Navier-Stokes equations.

# The Navier-Stokes Equations

$$\frac{\partial}{\partial t} \vec{u} - \nu \Delta \vec{u} + (\vec{u} \cdot \nabla) \vec{u} + \frac{1}{\rho_0} \nabla p = \vec{f}$$

$$\nabla \cdot \vec{u} = 0$$

Plus Boundary conditions, say periodic in the box

$$\Omega = [0, L]^3$$

- We will assume that  $\rho_0 = 1$
- Denote by  $\langle \varphi \rangle = \int_{\Omega} \varphi(x) dx$
- Observe that if  $\langle \vec{u}_0 \rangle = \langle \vec{f} \rangle = 0$  then  $\langle \vec{u} \rangle = 0$ .
- **Poncare' Inequality**

For every  $\varphi \in H^1$  with  $\langle \varphi \rangle = 0$  we have

$$\|\varphi\|_{L^2} \leq cL \|\nabla \varphi\|_{L^2}$$



# Sobolev Spaces

$$H^s(\Omega) = \left\{ \varphi = \sum_{\vec{k} \in \mathbb{Z}^d} \hat{\varphi}_{\vec{k}} e^{i\vec{k} \cdot \vec{x} \frac{2\pi}{L}} \right.$$

such that

$$\left. \sum_{\vec{k} \in \mathbb{Z}^d} \left| \hat{\varphi}_{\vec{k}} \right|^2 (1 + \left| \vec{k} \right|^2)^s < \infty \right\}$$

# Navier-Stokes Equations Estimates

- Formal Energy estimate

$$\frac{1}{2} \frac{d}{dt} \|\vec{u}\|_{L^2}^2 + \nu \|\nabla \vec{u}\|_{L^2}^2 + \int (\vec{u} \cdot \nabla) \vec{u} \cdot \vec{u} + \int \nabla p \cdot \vec{u} = (\vec{f}, \vec{u})$$

- Observe that since  $\nabla \cdot \vec{u} = 0$  we have

$$\int (\vec{u} \cdot \nabla) \vec{u} \cdot \vec{u} dx = \int \nabla p \cdot \vec{u} dx = 0$$

$$\Rightarrow \frac{1}{2} \frac{d}{dt} \|\vec{u}\|_{L^2}^2 + \nu \|\nabla \vec{u}\|_{L^2}^2 = (\vec{f}, \vec{u})$$

By the Cauchy-Schwarz and Poincare' inequalities

$$\frac{1}{2} \frac{d}{dt} \|\vec{u}\|_{L^2}^2 + \nu \|\nabla \vec{u}\|_{L^2}^2 \leq \|\vec{f}\|_{L^2}^2 \|\vec{u}\|_{L^2}^2 \leq cL \|\vec{f}\|_{L^2} \|\nabla \vec{u}\|_{L^2}$$

By the Young's inequality

$$\frac{1}{2} \frac{d}{dt} \|\vec{u}\|_{L^2}^2 + \nu \|\nabla \vec{u}\|_{L^2}^2 \leq \frac{cL^2}{\nu} \|\vec{f}\|_{L^2}^2 + \frac{\nu}{2} \|\nabla \vec{u}\|_{L^2}^2$$

$$\frac{1}{2} \frac{d}{dt} \|\vec{u}\|_{L^2}^2 + \frac{\nu}{2} \|\nabla \vec{u}\|_{L^2}^2 \leq \frac{cL^2}{\nu} \|\vec{f}\|_{L^2}^2$$

By Poincare' inequality

$$\frac{d}{dt} \|\vec{u}\|_{L^2}^2 + c \frac{\nu}{L^2} \|\vec{u}\|_{L^2}^2 \leq \frac{cL^2}{\nu} \|\vec{f}\|_{L^2}^2$$

By Gronwall's inequality

$$\|\vec{u}(t)\|_{L^2}^2 \leq e^{-c\nu L^{-2}t} \|\vec{u}(0)\|_{L^2}^2 + \frac{cL^4}{\nu^2} \left(1 - e^{-c\nu L^{-2}t}\right) \|\vec{f}\|_{L^2}^2 \quad \forall t \in [0, T]$$

and

$$\nu \int_0^T \|\nabla \vec{u}(\tau)\|_{L^2}^2 d\tau \leq K(L, \|\vec{u}_0\|_{L^2}, \|\vec{f}\|_{L^2}, \nu, T)$$

## Theorem (Leray 1932-34)

For every  $T > 0$  there exists a weak solution (in the sense of distribution) of the Navier-Stokes equations, which also satisfies

$$\vec{u} \in C_w([0, T], L^2(\Omega)) \cap L^2([0, T], H^1(\Omega))$$

The uniqueness of weak solutions in the three dimensional Navier-Stokes equations case is still an open question.

# Strong Solutions of Navier-Stokes

$$\vec{u} \in C([0, T], H^1(\Omega)) \cap L^2([0, T], H^2(\Omega))$$

## Enstrophy

$$\|\nabla \times \vec{u}\|_{L^2}^2 = \|\vec{\omega}\|_{L^2}^2 = \|\nabla \vec{u}\|_{L^2}^2$$

# Formal Enstrophy Estimates

$$\frac{1}{2} \frac{d}{dt} \|\nabla \vec{u}\|_{L^2}^2 + \nu \|\Delta \vec{u}\|_{L^2}^2 + \int (\vec{u} \cdot \nabla) \vec{u} \cdot (-\Delta \vec{u}) + \int \nabla p \cdot (-\Delta \vec{u}) = \int \vec{f} \cdot (-\Delta \vec{u})$$

Observe that  $\int \nabla p \cdot (-\Delta \vec{u}) dx = 0$

By Cauchy-Schwarz  $\left| \int \vec{f} \cdot (-\Delta \vec{u}) \right| \leq \frac{\|\vec{f}\|_{L^2}^2}{\nu} + \frac{\nu}{4} \|\Delta \vec{u}\|_{L^2}^2$

By Hölder inequality

$$\left| \int (\vec{u} \cdot \nabla) \vec{u} \cdot (-\Delta \vec{u}) \right| \leq \|\vec{u}\|_{L^4} \|\nabla \vec{u}\|_{L^4} \|\Delta \vec{u}\|_{L^2}$$

# Calculus/Interpolation (Ladyzhenskaya) Inequalities

$$\|\varphi\|_{L^4} \leq \begin{cases} c \|\varphi\|_{L^2}^{1/2} \|\nabla \varphi\|_{L^2}^{1/2} & 2-D \\ c \|\varphi\|_{L^2}^{1/4} \|\nabla \varphi\|_{L^2}^{3/4} & 3-D \end{cases}$$

Denote by  $y = e_0 + \|\nabla \vec{u}\|_{L^2}^2$



# The Two-dimensional Case

$$\dot{y} \leq c y^2 \quad \& \quad \int_0^T y(\tau) d\tau \leq K(T)$$

$$\Rightarrow y(t) \leq \tilde{K}(T)$$

Global regularity of strong solutions to the two-dimensional Navier-Stokes equations.

# Navier-Stokes Equations

- Two-dimensional Case
  - \* Global Existence and Uniqueness of weak and strong solutions
  - \* Finite dimension global attractor

# The Three-dimensional Case

Recall that  $y = e_0 + \|\nabla \vec{u}\|_{L^2}^2$

One can show that

$$\dot{y} \leq c(\|u\|_{L^6}^4 + e_0^2) y$$

Which implies that

$$y(t) \leq y(0) e^{c \int_0^t (\|u(\tau)\|_{L^6}^4 + e_0^2) d\tau}$$

The Question Is Again Whether:

$$\int_0^T \|u(\tau)\|_{L^6}^4 d\tau \leq K ?$$

One can instead use the following Sobolev inequality

$$\|\vec{u}\|_{L^6} \leq c \|\nabla \vec{u}\|_{L^2}$$

Which leads to

$$\dot{y} \leq cy^3 \quad \& \quad \int_0^T y(\tau) d\tau \leq K$$

### Theorem (Leray 1932-1934)

There exists  $T_*(\|\vec{u}_0\|_{L^2}, \|\vec{f}\|_{L^2}, \nu, L)$  such that

$y(t) < \infty$  for every  $t \in [0, T_*)$ .

# Navier-Stokes Equations

- The Three-dimensional Case
  - \* Global existence of the weak solutions
  - \* Short time existence of the strong solutions
  - \* Uniqueness of the strong solutions
- Open Problems:
  - \* Uniqueness of the weak solution
  - \* Global existence of the strong solution.

# Vorticity Formulation

$$\frac{\partial \vec{\omega}}{\partial t} - \nu \Delta \vec{\omega} + (\vec{u} \cdot \nabla) \vec{\omega} - \underline{\underline{(\vec{\omega} \cdot \nabla) \vec{u}}} = \nabla \times \vec{f}$$

**Vorticity Stretching Term**  $(\vec{\omega} \cdot \nabla) \vec{u}$

**Two dimensional case**  $(\vec{\omega} \cdot \nabla) \vec{u} \equiv \vec{0}$

$$\frac{\partial \vec{\omega}}{\partial t} - \nu \Delta \vec{\omega} + (\vec{u} \cdot \nabla) \vec{\omega} = \nabla \times \vec{f}$$

$|\vec{\omega}(x, t)|^2$  Satisfies a maximum principle.

## The Three-dimensional Case

$$(\vec{\omega} \cdot \nabla) \vec{u} \neq 0$$

$$\vec{\omega} \sim \mathbf{z}$$

$$(\vec{\omega} \cdot \nabla) \vec{u} \sim \mathbf{z}^2$$

For large initial data  $\vec{\omega}_0$  the vorticity balance takes the form

$$\dot{\mathbf{z}} \sim \mathbf{z}^2 \Rightarrow \text{Potential "Blow Up"!!}$$



## Euler Equations $\nu = 0$

### • Three-Dimensional case

$\exists T_*(\vec{u}_0)$  such that we have existence and uniqueness on  $[0, T_*)$ .

### • Beale-Kato-Majda

If  $\int_0^T \|\vec{\omega}(t)\|_{L^\infty} dt < \infty$  then we have existence and uniqueness on the interval  $[0, T]$

- That is, one has to “control” the  $\|\vec{\omega}(t)\|_{L^\infty}$  in some way!!

- **Constantin and Fefferman:**

Provided sufficient condition involving the Lipschitz regularity of the direction of the vorticity:

$$\omega_{\text{dir}} = \frac{\vec{\omega}}{|\vec{\omega}|}$$

## Two-Dimensions Euler

$$\frac{\partial \vec{\omega}}{\partial t} + (\vec{u} \cdot \nabla) \vec{\omega} = 0$$

$$\vec{u} = \nabla \times (\psi \vec{k})$$

$$\Delta \psi \vec{k} = \vec{\omega}$$

- **Yudovich** proved a weak version of the maximum principle, that is

$$\|\omega(t)\|_{L^\infty} \leq \|\omega_0\|_{L^\infty}.$$

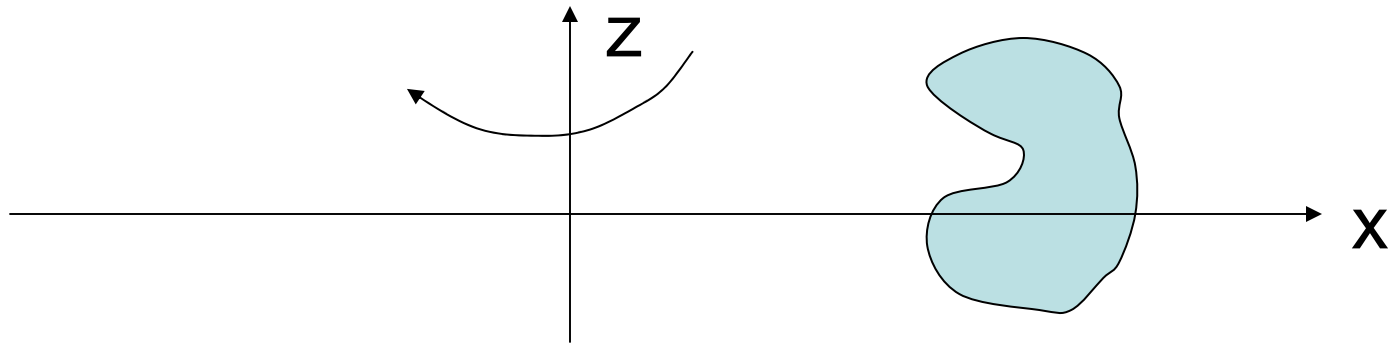
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$$\|\psi\|_{W^{2,p}} = \sum_{|\alpha| \leq 2} \|D^\alpha \psi\|_{L^p} \leq \underbrace{c \cdot p}_{\text{constant}} \|\Delta \psi\|_{L^p}$$

# Special Results of Global Existence for the three-dimensional Navier-Stokes

## Theorem (Kato)

Let  $\|u_0\|_{H^{1/2}}$  be small enough. Then the 3D Navier - Stokes equations are globally well - posed for all time with such initial data. The same result holds if the initial data is small in  $L^3(\Omega)$  (Kato, Giga & Miyakawa)



- $\Omega$  – Revolution Domain around the  $z$  - axis  
[away from  $z$  - axis]

- Let us move to Cylindrical coordinates

**Theorem (Ladyzhenskaya)** Let

$$\vec{u}_0(x, y, z) = (\varphi_r^0(r, z), \varphi_\theta^0(r, z), \varphi_z^0(r, z))$$

be axi-symmetric initial data. Then the three-dimensional Navier-Stokes equations have globally (in time) strong solution corresponding to such initial data. Moreover, such strong solution remains axi-symmetric.

## Theorem (Leiboviz, Mahalov and E.S.T.)

Consider the three-dimensional Navier-Stokes equations in an infinite Pipe. Let

$$\vec{u}_0 = (\varphi_r^0(r, n\theta + \alpha z), \varphi_\theta^0(r, n\theta + \alpha z), \varphi_z^0(r, n\theta + \alpha z))$$

(Helical symmetry). For such initial data we have global existence and uniqueness. Moreover, such a solution remains helically symmetric.

# Remarks

- For axi-symmetric and helical flows the vorticity stretching term is nontrivial, and the velocity field is three-dimensional.
- In the inviscid case, i.e.  $\nu = 0$ , the question of global regularity of the three-dimensional helical or axi-symmetrical Euler equations is still open. Except the invariant sub-spaces where the vorticity stretching term is trivial.

- **Theorem [Cannone, Meyer & Planchon]  
[Bondarevsky] 1996**

*Let  $M$  be given, as large as we want. Then there exists  $K(M)$  such that for every initial data of the form*

$$\vec{u}_0 = \sum_{|\vec{k}| \geq K(M)} \vec{\hat{u}}_{\vec{k}}^0 e^{i\vec{k} \cdot \vec{x} \frac{2\pi}{L}}$$

[VERY OSCILLATORY]

*the three-dimensional Navier-Stokes equations have global existence of strong solutions.*

**Remark** Such initial data satisfies  $\|\mathbf{u}_0\|_{H^{1/2}} \ll 1$ .

So, this is a particular case of Kato's Theorem.



# The Effect of Rotation

$$\frac{\partial \vec{u}}{\partial t} + (\vec{u} \cdot \nabla) \vec{u} + \nabla p + \vec{\Omega} \times \vec{u} = 0$$
$$\nabla \cdot \vec{u} = 0$$

- There is  $\Omega_0(T, \vec{u}_0)$  such that if  $|\Omega| > \Omega_0$  the solution exists on  $[0, T)$ .
- That is there exists  $T_0(\vec{u}_0, |\vec{\Omega}|)$  such that the solution exists on  $[0, T_0)$ . Observe that

$$T_0 \rightarrow \infty \text{ as } |\vec{\Omega}| \rightarrow \infty$$

- Babin - Mahalov - Nicolaenko.
- Embid - Majda.
- Chemin, Ghalagher, Granier, Masmoudi, ...
- Liu and Tadmor.

## An Illustrative Example

Inviscid Burgers Equation

$$u_t + uu_x = 0 \quad \text{in } \mathbb{R}$$

$$u(x, 0) = u_0(x)$$

- If  $u_0(x)$  is decreasing function on some subinterval of  $\mathbb{R}$  then the solution of the above equation develops a singularity (Shock) in finite time.

The solution is given implicitly by the relation:

$$u(x, t) = u_0(x - tu(x, t))$$

# The Effect of the Rotation

$$u \in \mathbf{C} \quad z \in \mathbf{C}$$

$$u_t + uu_z + i\Omega u = 0$$

$$u_0(z) = u(z, 0)$$

$$v(z, t) = e^{i\Omega t} u(z, t)$$

$$v_t + e^{-i\Omega t} v v_z = 0$$

$$v(z, t) = v_0 \left( z - \frac{e^{-i\Omega t} - 1}{-i\Omega} v(z, t) \right)$$

$$\frac{\partial}{\partial z} v = \frac{v_0' \left( z - \frac{e^{-i\Omega t} - 1}{-i\Omega} v(z, t) \right)}{1 + \frac{e^{-i\Omega t} - 1}{-i\Omega} v_0' \left( z - \frac{e^{-i\Omega t} - 1}{-i\Omega} v(z, t) \right)}$$

If  $\Omega \gg 1$ , (i.e.  $\Omega > \Omega_0(u_0)$ )

$\frac{\partial}{\partial z} v$  remains finite and the

solution remains regular for all  $t \geq 0$ .

**The above complex system is equivalent to 2D Rotating Burgers:**

$$u = u_1 + iu_2, \quad z = x + iy$$

$$\vec{u}_t + \vec{u} \cdot \nabla \vec{u} + \Omega \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \vec{u} = 0$$

More generally

- $u_t + \operatorname{div} F(u) = 0$  (Short time existence)

- $v_t + \underline{\underline{\cos(\Omega t)}} \operatorname{div} F(v) = 0$

For  $\Omega > \Omega_0(v_0)$  we have global existence.

Let  $\tau = \frac{\sin \Omega t}{\Omega}$  and denote by  $w(\tau, x) = v(t, x)$

Then

$$\begin{cases} w_\tau + \operatorname{div} F(w) = 0 \\ w(x, 0) = v_0(x) = u_0(x) \end{cases}$$

For  $\tau$  in the interval  $-T_*(v_0) \leq \tau \leq T_*(v_0)$  the solution  $w$

exists. That is whenever  $t$  satisfies  $-T_*(v_0) \leq \frac{\sin(\Omega t)}{\Omega} \leq T_*(v_0)$

# Bénard Convection Porous Medium

$$\left\{ \begin{array}{l} \gamma \frac{\partial}{\partial t} \vec{u} + \vec{u} + \nabla p - RT\vec{k} = 0 \\ \nabla \cdot \vec{u} = 0 \\ \frac{\partial}{\partial t} T - \kappa \Delta T + (\vec{u} \cdot \vec{\nabla}) T = 0 \end{array} \right.$$

Subject to certain physical boundary conditions.

- P. Fabrie [1986] Global Existence & Uniqueness
- H.V. Ly E.S.T. [1999] ( $\gamma = 0$ )

Same result based on Galerkin numerical procedure.

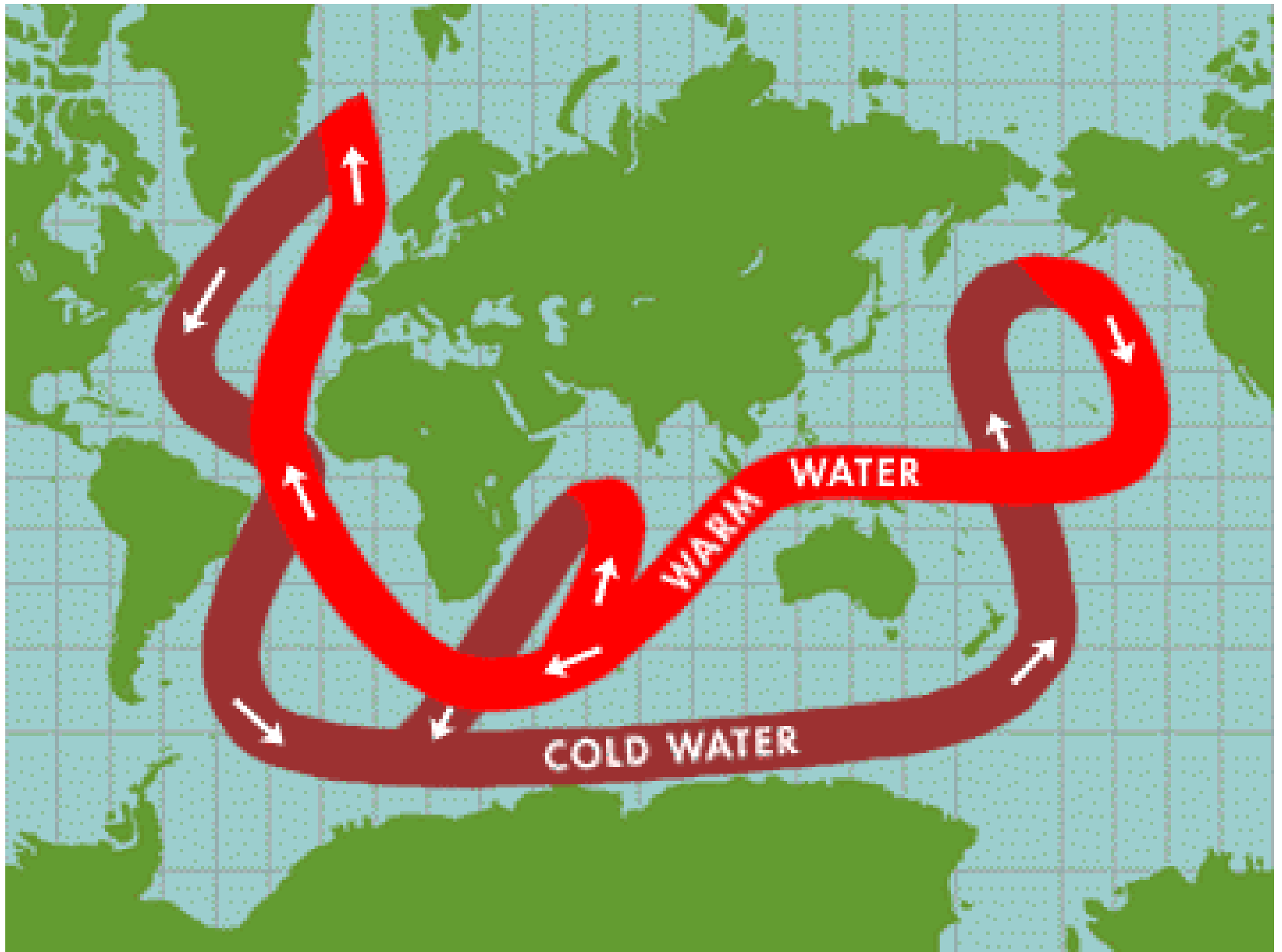
This gives leads to Spatial Analyticity, and exponential rate of convergence of the Galerkin procedure.

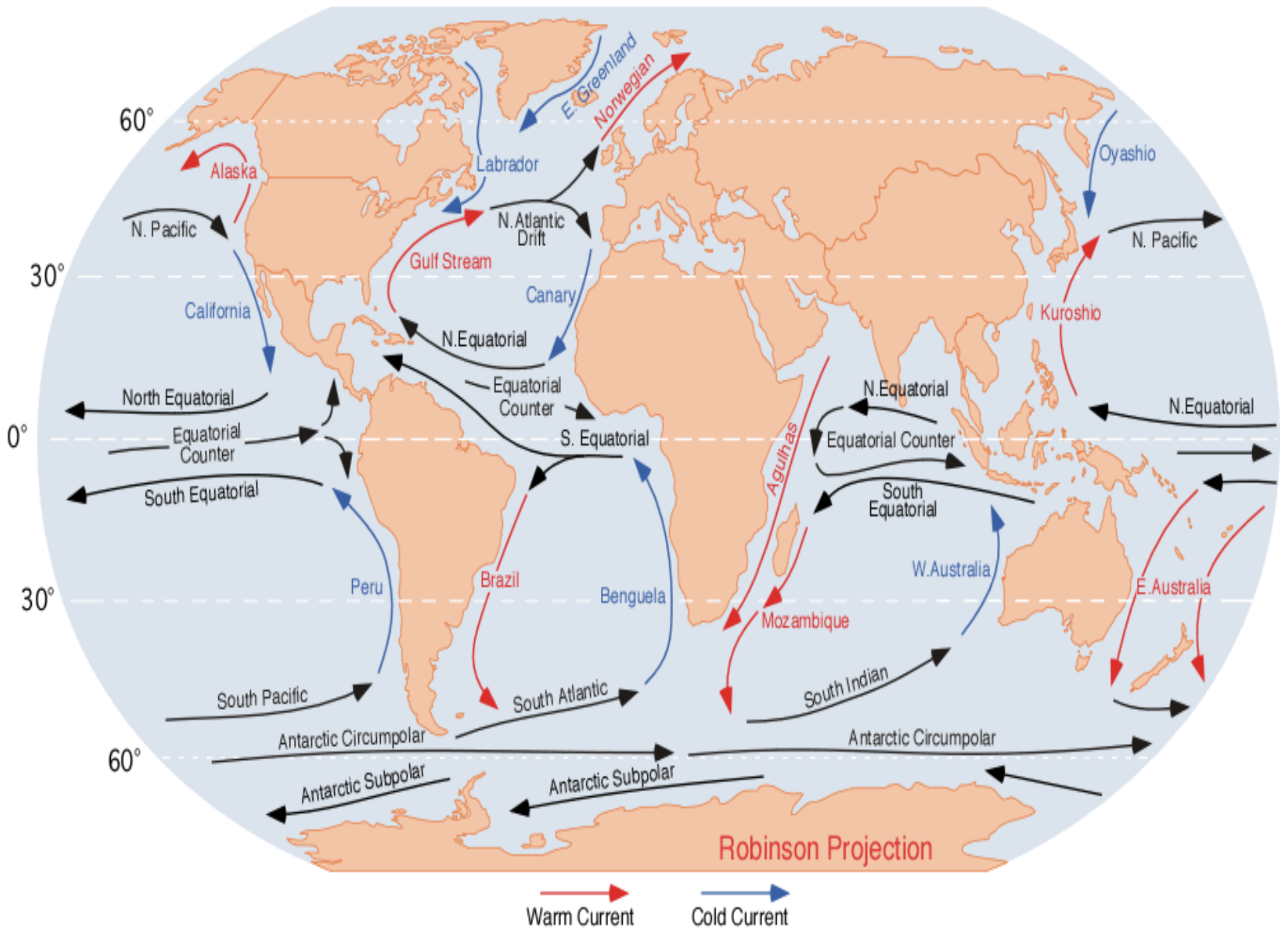
- M. Oliver and E.S.T. ( $\gamma > 0$ )

Spatial analyticity of the attractor.



# Large Scale Oceanic Circulations





# Be'nard Convection/Boussinesq Approximation

$$\frac{\partial}{\partial t} v_H - \nu \left( \Delta_H + \frac{\partial^2}{\partial z^2} \right) v_H + (v_H \cdot \nabla_H) v_H + w \frac{\partial}{\partial z} v_H + \frac{1}{\rho_0} \nabla_H p + f \vec{k} \times v_H = 0$$

$$\frac{\partial}{\partial t} w - \nu \left( \Delta_H + \frac{\partial^2}{\partial z^2} \right) w + (v_H \cdot \nabla_H) w + w \frac{\partial}{\partial z} w + \frac{1}{\rho_0} \frac{\partial}{\partial z} p + T g = 0$$

$$\nabla_H \cdot v_H + \frac{\partial}{\partial z} w = 0$$

$$\frac{\partial}{\partial t} T - \kappa \Delta T + (v_H \cdot \nabla_H) T + w \frac{\partial}{\partial z} T = \rho_0 Q$$

Here  $(v_H, w) = \vec{u}$ .

# Typical Scales in the Ocean

- horizontal distance  $L \sim 10^6$  m
- horizontal velocity  $U \sim 10^{-1}$  m/s
- depth  $H \sim 10^3$  m
- Coriolis parameter  $f \sim 10^{-4}$  1/s
- gravity  $g \sim 10$  m/s<sup>2</sup>
- density  $\rho_0 \sim 10^3$  kg/m<sup>3</sup>

# Calculating the typical values

- Typical vertical velocity  $W = UH/L \sim 10^4 \text{ m/s}$
- Typical pressure  $P = \rho_0 gH \sim 10^7 \text{ Pa}$
- Typical time scale  $T = L/U \sim 10^7 \text{ s}$

# Scale Analysis of Vertical Motion – The Ideal Case

$$\frac{\partial}{\partial t} w + (v_H \cdot \nabla_H) w + w \frac{\partial}{\partial z} w + \frac{1}{\rho_0} \frac{\partial}{\partial z} p + Tg = 0$$

$$\frac{W}{T} + \frac{UW}{L} + \frac{W^2}{H} + \frac{P}{H\rho_0} + Tg = 0$$

$$10^{-11} + 10^{-11} + 10^{-11} + 10 + 10 = 0$$

# Hydrostatic Balance

$$\frac{1}{\rho_0} \frac{\partial}{\partial z} p + Tg = 0$$



# Scale Analysis – The Ideal Case

$$\frac{\partial}{\partial t} v_H + (v_H \cdot \nabla_H) v_H + w \frac{\partial}{\partial z} v_H + \frac{1}{\rho_0} \nabla_H p + f \vec{k} \times v_H = 0$$

$$\frac{U}{T} + \frac{U^2}{L} + \frac{UW}{H} + \frac{P}{L\rho_0} + UF = 0$$

$$10^{-8} + 10^{-8} + 10^{-8} + 10^{-2} + 10^{-5} = 0$$

# Rossby Number

$$R = \frac{U}{FL}$$

# Geostrophic Balance

- When  $R \ll 1$

$$\frac{1}{\rho_0} \nabla_H p + f \vec{k} \times v_H = 0$$

# The Ideal Planetary Geostrophic equations

$$\frac{1}{\rho_0} \nabla_H p + f \vec{k} \times \mathbf{v}_H = 0$$

$$\frac{1}{\rho_0} \partial_z p + Tg = 0$$

$$\nabla_H \cdot \mathbf{v}_H + \partial_z w = 0$$

$$T_t + (\mathbf{v}_H \cdot \nabla_H) T + w T_z = \rho_0 Q + \kappa \partial_{zz} T$$

# Rayleigh Friction and Horizontal-Diffusion

$$\frac{1}{\rho_0} \nabla_H p + f \vec{k} \times v_H = F(v_H)$$

$$\frac{1}{\rho_0} \partial_z p + Tg = 0$$

$$\nabla_H \cdot v_H + \partial_z w = 0$$

$$T_t + (v_H \cdot \nabla_H)T + w \partial_z T = \rho_0 Q + \kappa_v \partial_{zz} T + D(T)$$

# Friction, Viscosity and Diffusion Schemes

- Conventional eddy viscosity

$$F(v_H) = A_v \Delta_H v_H + A_h \partial_{zz} v_H \quad \text{and} \quad D(T) = \kappa_H \Delta_H T$$

- Linear drag

$$F(v_H) = -\epsilon v_H$$

What should be the diffusion operator D?

# The Viscous PG Equations

$$\frac{1}{\rho_0} \nabla_H p + f \vec{k} \times \mathbf{v}_H = K_v \Delta_H \mathbf{v}_H + K_h \partial_{zz} \mathbf{v}_H$$

$$\frac{1}{\rho_0} \partial_z p + Tg = 0$$

$$\nabla_H \cdot \mathbf{v}_H + \partial_z w = 0$$

$$T_t + (\mathbf{v}_H \cdot \nabla_H) T + w T_z = \rho_0 Q + \kappa_h \Delta_H T + \kappa_v \partial_{zz} T$$

# The Viscous PG Equations

## Weak Solutions

$$T \in C_w([0, T], L^2) \cap L^2([0, T], H^1)$$

## Strong Solutions

$$T \in C([0, T], H^1) \cap L^2([0, T], H^2)$$



# Results

- Samelson, Temam and Wang (1998)
  - \* the existence of the weak solutions,  
but no uniqueness,
  - \* the short time existence of the strong solutions.
- Samelson, Temam and Wang (2000)
  - \* global existence of the strong solution if  
initial data is bounded, i.e. in  $L^\infty$ .

# Results

- Cao and E.S.T. (2003)
  - \* the uniqueness of weak solutions
  - \* the global existence of the strong solutions for any initial data in  $H^1$
  - \* existence of the global attractor.
  - \* upper bounds for the dimension of the global attractor.

# Existence of Global Attractor

- Absorbing Ball  $\mathbf{B}$  in  $L^2$  (energy estimate)
- Absorbing Ball  $\mathbf{B}$  in  $H^1$  (energy estimate and the uniform Gronwall inequality)

$$A = \bigcap_{s>0} \bigcup_{t>s} S(t)\mathbf{B} \subset H^1.$$

# The Rayleigh Friction Case

$$\frac{1}{\rho_0} \nabla_H p + f \vec{k} \times \mathbf{v}_H = -\varepsilon \mathbf{v}_H$$

$$\frac{1}{\rho_0} \partial_z p + Tg = 0$$

$$\nabla_H \cdot \mathbf{v}_H + \partial_z w = 0$$

$$T_t + (\mathbf{v}_H \cdot \nabla_H) T + w T_z = \rho_0 Q + \kappa_h \Delta_H T + \kappa_v \partial_{zz} T$$

# Natural Boundary Conditions

- no normal flow

$$\vec{v}_H \cdot \vec{n} = 0 \quad \text{on side and} \quad w=0 \quad \text{when } z=-h, 0$$

- no heat-flux

$$\frac{\partial T}{\partial \vec{n}} = 0 \quad \text{on the side and}$$

$$\partial_z T = 0 \quad \text{when } z = -h, 0$$

The no - flow boundary condition

$$\vec{v}_H \cdot \vec{n} |_{\Gamma_s} = 0 \quad \text{implies that}$$

$$\frac{\partial T}{\partial \vec{e}} |_{\Gamma_s} = 0 \quad \text{where } \vec{e} = \frac{1}{\sqrt{\varepsilon^2 + f^2}} (\varepsilon n_1 - f n_2, f n_1 - \varepsilon f_2)$$

this is in addition to the no - heat flux boundary

condition  $\frac{\partial T}{\partial \vec{n}} |_{\Gamma_s} = 0$

Therefore, there are **two boundary conditions** for the temperature which is governed by a **second order parabolic PDE**. So it is over-determined, and the problem is ill-posed. This is consistent with the numerical instability observed using this system.

# Rayleigh Friction and Temperature Horizontal Hyper-Diffusion Model

We therefore propose the following artificial Horizontal Hyper-diffusion model

$$\frac{1}{\rho_0} \nabla_H p + f \vec{k} \times v_H = -\varepsilon v_H$$

$$\frac{1}{\rho_0} \partial_z p + Tg = 0$$

$$\nabla_H \cdot v_H + \partial_z w = 0$$

$$T_t + (v_H \cdot \nabla_H)T + wT_z = \rho_0 Q + \nabla_H \cdot q(T) + \kappa \partial_{zz} T$$

# With the Boundary Conditions

- no normal flow

$$\vec{v}_H \cdot \vec{n} = 0 \text{ on side } \Gamma_s, \text{ \& } w = 0 \text{ when } z = -h, 0$$

- no heat-flux

$$q(T) \cdot \vec{n} = 0 \text{ on the side and}$$

$$\partial_z T = 0 \text{ when } z = -h, 0$$



# Proposed Artificial Hyper-Diffusion

$$\mathbf{H} = \begin{pmatrix} 1 & -\mathbf{f}/\varepsilon \\ \mathbf{f}/\varepsilon & 1 \end{pmatrix}$$

$$\begin{aligned} \mathbf{q}(\mathbf{T}) = & \lambda \mathbf{H} \nabla_H \left( \nabla_H \cdot (\mathbf{H}^T \nabla_H \mathbf{T}) \right) + \mu \nabla_H \mathbf{T}_{zz} \\ & - \mathbf{K}_h \nabla_H \mathbf{T} \end{aligned}$$

Which is positive definite (dissipative/stabilizing) with the associate boundary conditions.

# Hyper Horizontal Diffusion Model

Weak Solutions

$$\vec{u} \in C_w([0, T], L^2), \quad \Delta \vec{u} \in L^2([0, T], L^2)$$

Strong Solutions

$$\nabla \vec{u} \in L^\infty([0, T], H^1), \quad \Delta \vec{u} \in L^2([0, T], H^2)$$

# Results

- Cao, E.S.T., Ziane (2004)
  - \* The global existence and uniqueness of the weak solutions.
  - \* The global existence of the strong solutions.
  - \* Existence of the global attractor.
  - \* Provide upper bounds for the dimension of the global attractor.

# Recall Scale Analysis of Vertical Motion –The Ideal Case

$$\frac{\partial}{\partial t} w + (v_H \cdot \nabla_H) w + w \frac{\partial}{\partial z} w + \frac{1}{\rho_0} \frac{\partial}{\partial z} p + Tg = 0$$

$$\frac{W}{T} + \frac{UW}{L} + \frac{W^2}{H} + \frac{P}{H\rho_0} + Tg = 0$$

$$10^{-11} + 10^{-11} + 10^{-11} + 10 + 10 = 0$$

# Recall Scale Analysis for Horizontal Motion – The Ideal Case

$$\frac{\partial}{\partial t} v_H + (v_H \cdot \nabla_H) v_H + w \frac{\partial}{\partial z} v_H + \frac{1}{\rho_0} \nabla_H p + f \vec{k} \times v_H = 0$$

$$\frac{U}{T} + \frac{U^2}{L} + \frac{UW}{H} + \frac{P}{L\rho_0} + UF = 0$$

$$10^{-8} + 10^{-8} + 10^{-8} + 10^{-2} + 10^{-5} = 0$$

# The Primitive Equations of Large Scale Oceanic and Atmospheric Dynamics

$$\begin{aligned}\partial_t \mathbf{v}_H + (\mathbf{v}_H \cdot \nabla_H) \mathbf{v}_H + w \partial_z \mathbf{v}_H + \nabla_H p + f \vec{k} \times \mathbf{v}_H \\ = A_h \Delta_H \mathbf{v}_H + A_v \partial_{zz} \mathbf{v}_H\end{aligned}$$

$$\partial_z p + gT = 0$$

$$\nabla_H \cdot \mathbf{v}_H + \partial_z w = 0$$

$$T_t + (\mathbf{v}_H \cdot \nabla_H) T + w T_z = Q + K_h \Delta_H T + K_v T_{zz}$$

- Introduced by Richardson (1922)  
For Weather Prediction
- J.L. Lions, R. Temam, S. Wang (1992)  
Gave Some Asymptotic Derivation of the  
Model.

# Primitive Equations

Weak Solutions

$$\vec{u} \in C_w([0, T], L^2) \cap L^2([0, T], H^1)$$

Strong Solutions

$$\vec{u} \in L^\infty([0, T], H^1) \cap L^2([0, T], H^2)$$



# Previous Results

- J.L. Lions, Temam, S. Wang (1992), and Temam, Ziane (2003)  
The global existence of the weak solutions (No Uniqueness).
- Guillen-Gonzalez, Masmoudi, Rodriguez-Bellido (2001), and Temam, Ziane (2003)  
The short time existence of the strong solution
- Temam, Ziane (2003)  
Global Existence of Strong Solution for the 2-D case.
- C. Hu, Temam, Ziane (2003)  
Global Regularity for Restricted (Large) Initial Data in Thin Domains.

# Results

- Cao and E.S.T. *Annals of Mathematics* (2007) (to appear)
  - \* the global existence of the weak solutions (Galerkin method)
  - \* the global existence and uniqueness of the strong solutions.
  - \* existence of the global attractor.
  - \* upper bound for the dimension of the global attractor.

# A different formulation of the PE

$$w(x, y, z) = -\int_{-h}^z \nabla_H \cdot v_H(x, y, \xi) d\xi$$

$$p(x, y, z) = p_s(x, y) - g \int_{-h}^z T(x, y, \xi) d\xi$$

$$\bar{v}_H(x, y) = \frac{1}{h} \int_{-h}^0 v_H(x, y, \xi) d\xi, \quad \nabla_H \cdot \bar{v}_H = 0$$

$$\tilde{v}_H(x, y, z) = v_H(x, y, z) - \bar{v}_H(x, y)$$

# The Barotropic Mode – The Averaged Part of the Horizontal Velocity

$$\begin{aligned} \partial_t \bar{v}_H + \overline{(v_H \cdot \nabla_H) v_H} + \overline{w \partial_z v_H} + f \vec{k} \times \bar{v}_H + \nabla_H p_s \\ = A_h \Delta_H \bar{v}_H + \nabla_H \int_{-h}^z T dz \end{aligned}$$

# The Baroclinic Mode –The Fluctuation Part of the Horizontal Velocity

$$\begin{aligned}
 & \partial_t \tilde{v}_H + (\tilde{v}_H \cdot \nabla_H) \tilde{v}_H + (\tilde{v}_H \cdot \nabla_H) \bar{v}_H + (\bar{v}_H \cdot \nabla_H) \tilde{v}_H + \\
 & \left( - \int_{-h}^z \nabla_H \cdot v_H dz \right) \partial_z \tilde{v}_H + f \vec{k} \times \tilde{v}_H - \\
 & \overline{(\tilde{v}_H \cdot \nabla_H) \tilde{v}_H + (\nabla_H \cdot \tilde{v}_H) \tilde{v}_H} = \\
 & A_h \Delta_H \tilde{v}_H + A_v \partial_{zz} \tilde{v}_H + \nabla_H \int_{-h}^z gT d\xi - \nabla_H \overline{\int_{-h}^z gT d\xi}
 \end{aligned}$$

# The IDEA – Focus on Burgers Equation

$$u_t - \nu \Delta u + (u \cdot \nabla) u = 0$$

We have

$$\frac{1}{2} \partial_t |u(x, t)|^2 - \frac{1}{2} \Delta |u(x, t)|^2 + \sum_{i, j} \left( \frac{\partial u_i}{\partial x_j} \right)^2 + \frac{1}{2} u \cdot \nabla |u(x, t)|^2 = 0$$

A maximum principle for  $|u(x, t)|^2$  and  $L^\infty$  bound.

Global Regularity for 1D, 2D and 3D Burgers Equation.

# The Pressure Term!!

- Is the major difference between Burgers and the Navier-Stokes equations.
- What about in our system?

The Averaged Equation is “like” the  
2D Navier-Stokes.

$$\begin{aligned} \partial_t \bar{v}_H + \overline{(v_H \cdot \nabla_H) v_H} + \overline{w \partial_z v_H} + f \vec{k} \times \bar{v}_H + \nabla_H p_s \\ = A_h \Delta_H \bar{v}_H + \nabla_H \int_{-h}^z T dz \end{aligned}$$

Where  $p_s(x, y)!!$



# The Fluctuation Equation is “like” 3D Burgers Equations – Has No Pressure Term!!

$$\begin{aligned}
 & \partial_t \tilde{\mathbf{v}}_H + (\tilde{\mathbf{v}}_H \cdot \nabla_H) \tilde{\mathbf{v}}_H + (\tilde{\mathbf{v}}_H \cdot \nabla_H) \bar{\mathbf{v}}_H + (\bar{\mathbf{v}}_H \cdot \nabla_H) \tilde{\mathbf{v}}_H + \\
 & \left( - \int_{-h}^z \nabla_H \cdot \mathbf{v}_H dz \right) \partial_z \tilde{\mathbf{v}}_H + f \vec{k} \times \tilde{\mathbf{v}}_H - \\
 & \overline{(\tilde{\mathbf{v}}_H \cdot \nabla_H) \tilde{\mathbf{v}}_H + (\nabla_H \cdot \tilde{\mathbf{v}}_H) \tilde{\mathbf{v}}_H} \\
 & = A_h \Delta_H \tilde{\mathbf{v}}_H + A_v \partial_{zz} \tilde{\mathbf{v}}_H + \nabla_H \int_{-h}^z gT d\xi - \nabla_H \overline{\int_{-h}^z gT d\xi}
 \end{aligned}$$

# A-priori Estimates

- $\left\| \tilde{v}_H \right\|_{L^6} \leq K$

- $\left\| \nabla_H \bar{v}_H \right\|_{L^2} \leq K$

$$\Rightarrow \left\| \bar{v}_H \right\|_{L^6} \leq K$$

$$\Rightarrow \left\| v_H \right\|_{L^6} = \left\| \bar{v}_H + \tilde{v}_H \right\|_{L^6} \leq K$$

Q.E.D.

# One of the Main Estimates Used

$$\left| \int_{\Omega} \left[ \left( \int_{-h}^0 u(x, y, z) dz \right) f(x, y, z) g(x, y, z) \right] dx dy dz \right|$$
$$\leq C \|u\|_{L^2(\Omega)}^{1/2} \|u\|_{H^1(\Omega)}^{1/2} \|f\|_{L^2(\Omega)}^{1/2} \|f\|_{H^1(\Omega)}^{1/2} \|g\|_{L^2(\Omega)}$$

# Back to The 3D Navier-Stokes Equations

$$\frac{\partial}{\partial t} \vec{u} - \nu \Delta \vec{u} + (\vec{u} \cdot \nabla) \vec{u} + \frac{1}{\rho_0} \nabla p = \vec{f}$$

$$\nabla \cdot \vec{u} = 0$$

# New Criterion for Global Regularity of the 3D Navier-Stokes Equations

Theorem (C. Cao and E.S.T. 2005) :

The strong solution of the 3D Navier - Stokes equations exists on the the interval  $[0, T]$  for as long as  $\partial_z p \in L^r((0, T), L^s(\Omega))$ , where  $r > 3$  and  $s > 2$ .

This is different that the result of Y. Zhou (2005) where the assumption is on  $\nabla p$ .

# Inviscid Regularization of the 3D Euler Equations

$$-\alpha^2 \Delta \frac{\partial}{\partial t} \vec{u} + \frac{\partial}{\partial t} \vec{u} + (\vec{u} \cdot \nabla) \vec{u} + \frac{1}{\rho_0} \nabla p = 0$$

$$\nabla \cdot \vec{u} = 0$$

# Modified Energy

$$\int (|u(x, t)|^2 + \alpha^2 |\nabla u(x, t)|^2) dx = \text{const.}$$

# Inviscid Regularization of the Surface Quasi-Geostrophic

$$-\alpha^2 \Delta \theta_t + \theta_t + u \cdot \nabla \theta = 0$$

$$u = \nabla^\perp (-\Delta)^{-1/2} \theta$$